



The exam consists of 4 questions. You have 120 minutes to do the exam. You can achieve 50 points in total which includes a bonus of 5 points.

1. [3+3+3=9 Points]

Each of the following time-continuous one-dimensional systems depends on a parameter  $a \in \mathbb{R}$ . Describe the bifurcations involved, sketch the corresponding bifurcation diagrams including representative one-dimensional phase portraits, and classify the bifurcations.

(a)  $x' = x^2 + ax$

(b)  $x' = ax - x^3$

(c)  $x' = x^3 - x - a$

2. [8 Points]

Consider the planar systems

$$X' = \begin{pmatrix} a & 1 \\ b & a \end{pmatrix} X$$

with parameters  $a, b \in \mathbb{R}$ . Sketch the regions in the  $a - b$  plane where this system has different types of canonical forms. In each region give the canonical form and sketch the phase portrait of the system in canonical form.

3. [1+2+4+4+2=13 Points]

Consider the planar system

$$\begin{aligned} x' &= y, \\ y' &= -\nu y - 4x^3 + 4x, \end{aligned}$$

where  $\nu \geq 0$  is a parameter.

(a) Show that the system has the three equilibrium points  $(x_-, y_-) = (-1, 0)$ ,  $(x_0, y_0) = (0, 0)$  and  $(x_+, y_+) = (1, 0)$ .

(b) Show from the linearization at  $(x_0, y_0) = (0, 0)$  that this equilibrium is a saddle.

(c) Show that for  $\nu = 0$ , the system is Hamiltonian with Hamilton function

$$H(x, y) = \frac{1}{2}y^2 + x^4 - 2x^2 + 1$$

and sketch the phase portrait in the  $x - y$  plane.

(d) Show that for  $\nu \geq 0$  and each  $0 < h < 1$ ,  $H$  is a Lyapunov function in the region  $D_h = \{(x, y) \in \mathbb{R}^2 \mid H(x, y) \leq h, x < 0\}$  and use the Lasalle Invariance Principle to show that for  $\nu > 0$ , the equilibrium at  $(x_-, y_-) = (-1, 0)$  is asymptotically stable with  $D_h$  belonging to the basin of attraction.

- (e) Sketch the phase portrait for  $\nu > 0$  by paying attention to the stable and unstable curves of the saddle at  $(x_0, y_0) = (0, 0)$ . What can you say about the basin of attraction of  $(x_-, y_-) = (-1, 0)$ .

4. [9+6=15 Points]

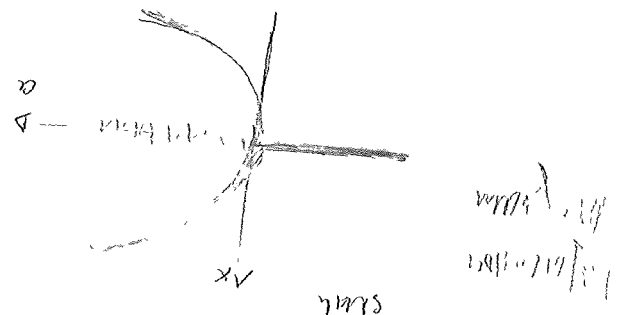
- (a) Show by direct proof (i.e. without using a conjugacy) that the discrete-time system  $x_{n+1} = t(x_n)$ ,  $n \in \mathbb{Z}_{\geq 0}$ , defined by the tent map

$$t : [0, 1] \rightarrow [0, 1], \quad x \mapsto \begin{cases} 2x & \text{if } x \leq \frac{1}{2} \\ 2 - 2x & \text{if } x > \frac{1}{2} \end{cases}$$

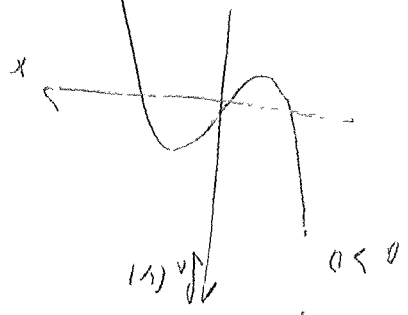
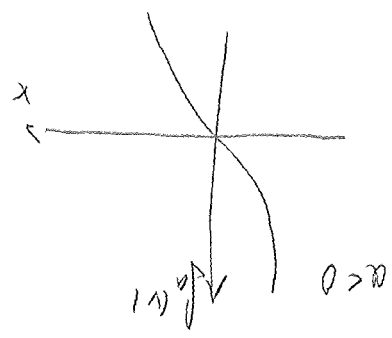
satisfies all three conditions of Devaney's definition of chaos.

- (b) Let  $I \subset \mathbb{R}$  and  $J \subset \mathbb{R}$  be compact intervals and suppose the two discrete-time systems  $x_{n+1} = f(x_n)$  and  $y_{n+1} = g(y_n)$  defined by maps  $f : I \rightarrow I$  and  $g : J \rightarrow J$  are topologically conjugate. Show that if the discrete-time system  $x_{n+1} = f(x_n)$ ,  $n \in \mathbb{Z}_{\geq 0}$ , is topologically transitive, then the discrete-time system  $y_{n+1} = g(y_n)$ ,  $n \in \mathbb{Z}_{\geq 0}$ , is also topologically transitive.

stabile Gleichgewichtspunkte  
 instabil und nicht  
 stabile Gleichgewichtspunkte  
 (supercritical) pitchfork bifurcation



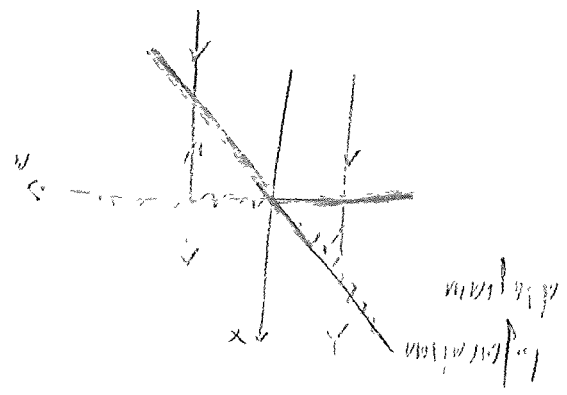
stabil, wenn  $\lambda < 0$   
 $\lambda > 0$



$\Rightarrow x=0 \vee x = \pm \sqrt{a}$   
 für  $a > 0$  sind  $\pm \sqrt{a}$  stabile  
 Gleichgewichtspunkte

(b)  $f_a(x) = ax - x^3$   $\lambda_a(x) = 0 \Rightarrow x = 0 \vee x = \pm \sqrt{a}$

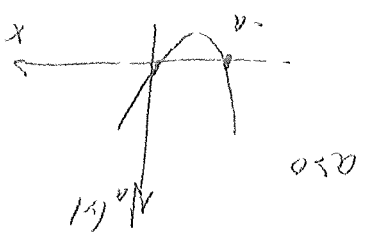
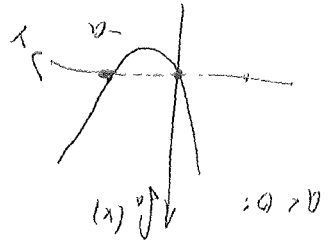
für  $a > 0$  sind  $\pm \sqrt{a}$  stabile  
 Gleichgewichtspunkte  
 für  $a < 0$  sind  $x=0$  instabil



$\lambda_a(x) = 0$   
 $\lambda_a(x) = 3x^2$

stabil, wenn  $\lambda < 0$   
 $\lambda > 0$

stabil, wenn  $\lambda < 0$   
 $\lambda > 0$



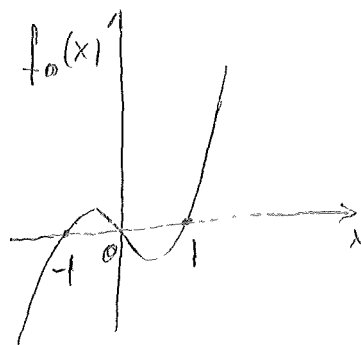
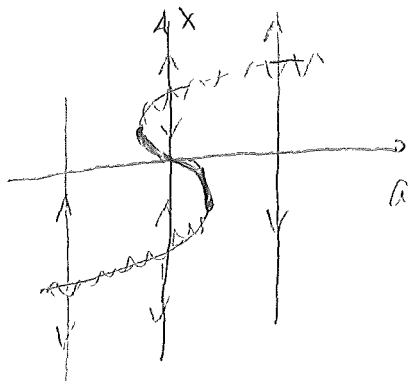
Equilibria:  $\lambda_a(x) = 0 \Rightarrow x = 0 \vee x = \pm \sqrt{a}$

(a)  $f_a(x) = x^3 - ax$

$\lambda_a(x) = 3x^2 - a$

(c)  $f_a(x) = x^3 - x - a$  equilibria:  $a - x^3 - x$

bifurcation diagram



two saddle node bifurcations

where two equilibria of opposite stability  
collide and get extinct

2. let  $A = \begin{pmatrix} a & 1 \\ b & a \end{pmatrix}$ .

characteristic polynomial:  $p(\lambda) = (a-\lambda)^2 - b$

eigenvalues:  $(a-\lambda)^2 - b = 0$

$\Leftrightarrow a - \lambda_{\pm} = \pm \sqrt{b}$

$\Leftrightarrow \lambda_{\pm} = a \pm \sqrt{b}$

$b < 0$ : eigenvalues complex with  $\text{Re } \lambda_{\pm} = a$

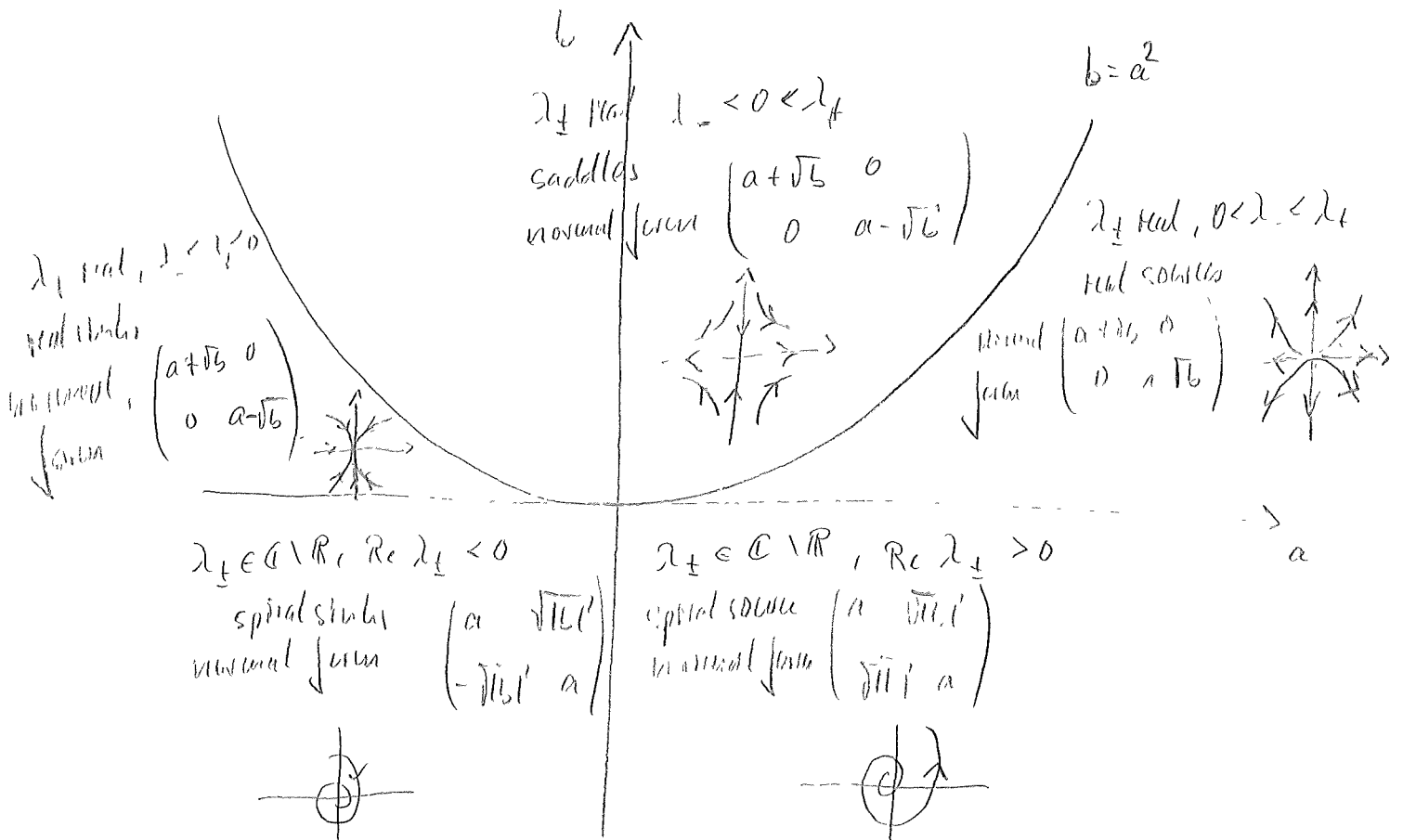
$a < 0$ : spiral sink

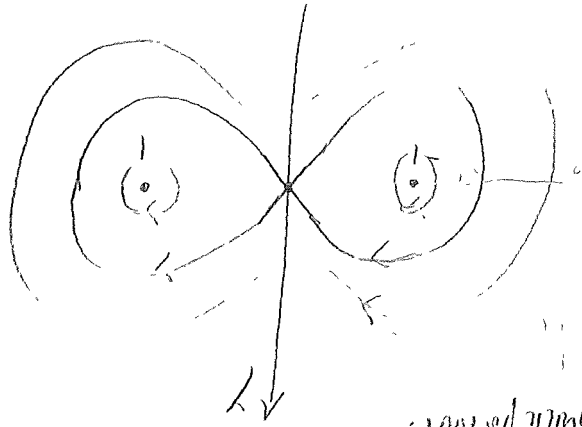
$a > 0$ : spiral source

normal form  $\begin{pmatrix} a & \sqrt{|b|} \\ -\sqrt{|b|} & a \end{pmatrix}$

$b > 0$ : eigenvalues real  $\lambda_{+} > 0 \Leftrightarrow a > -\sqrt{b}$

$\lambda_{-} < 0 \Leftrightarrow a < \sqrt{b}$





nots solution curves  
and level sets of  $H$

phase portrait:

which gives us the phase portrait for  $\lambda = 0$

$$x_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} x_2$$

(c) to be shown

it always holds that  $\lambda_2 < 0 < \lambda_1$   
could give a saddle

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= \begin{pmatrix} \lambda_1 x \\ \lambda_2 y \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \text{ which has eigenvalues}$$

(b) Linearization at  $(x_0, y_0)$  gives matrix

$$(x_0, y_0) = (0, 0)$$

$$(x_1, y_1) = (1, 0)$$

$$(x_2, y_2) = (-1, 0)$$

$$\text{for } x=0 \text{ or } x \neq 1$$

Then  $y' = -4x^2 + 4x$  which vanishes

$$(a) \text{ equilibria: } x' = 0 \Rightarrow y = 0$$

(d)  $H(-1, 0) = 0$

$H(0, 0) = 1$

$\dot{H} = \frac{\partial H}{\partial x} x' + \frac{\partial H}{\partial y} y' = -\nu y^2 \leq 0$

$\Rightarrow H$  Lyapunov function on  $D_h$ .

$D_h$  is compact and positively invariant

as  $D_h$  is enclosed by a level set of  $H$  and

is invariant under the flow.  $D_h$  is the period

of the flow.

$\Rightarrow$   $\dot{H} = 0 \Leftrightarrow y = 0$  is invariant. It is the

set of equilibrium solutions  $(-1, 0)$  and  $(0, 0)$ .

$\dot{H} = 0 \Leftrightarrow y(t) = 0$  f.a.t.

Then  $x'(t) - y(t) = 0$  f.a.t.

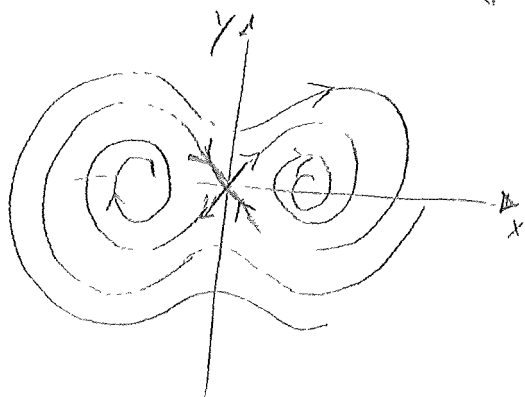
$\therefore x(t) = \text{const}$  f.a.t.

But the only solution  $(x(t), y(t)) = (\text{const}, 0)$

is the equilibrium solution  $(x(t), y(t)) = (-1, 0)$

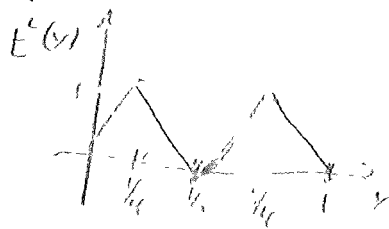
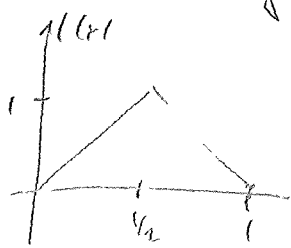
By LaSalle Invariance Principle,  $(-1, 0)$  is asymptotically stable and  $D_h$  is part of the basin of attraction.

(e)



The basin of attraction is bigger than  $D_h$ .

4 (a) Consider the graph of  $t$  and its iterates.



$t^n$  maps the  $2^n$  intervals

$$I_k^n := \left[ (k-1)\left(\frac{1}{2}\right)^n, k\left(\frac{1}{2}\right)^n \right], \quad k=1, \dots, 2^n$$

respectively to the interval  $[0, 1]$

(1) hence  $[0, 1] = \bigcup_{k=1}^{2^n} I_k^n$  and length of  $I_k^n$  equal to  $\left(\frac{1}{2}\right)^n$

1. Each interval  $I_k^n$  contains precisely points

$\Rightarrow$  precise preimages arise

2. Let  $U, V \subset [0, 1]$  open

$\Rightarrow \exists u, v \in \mathbb{R}, \exists \delta, \epsilon > 0$  s.t.  $U = (u, u+\delta)$

recall  $t^{-n}(I_k^n) = [0, 1]$

$\Rightarrow \exists x \in I_k^n \subset U$  s.t.  $t^n(x) \in V$

$\Rightarrow t$  transitive

3. choose  $\beta = \frac{1}{2}$ . Let  $x \in [0, 1]$  and  $U$  be open neighborhood of  $x$  to be chosen  $\exists \delta > 0$  and we choose  $\epsilon > 0$  such that

$$|t^n(x) - t^n(y)| < \epsilon$$

to this end note that  $\exists u, k \in \mathbb{N}_{>0}$  s.t.  $x \in I_k^u$  and  $I_k^u \subset U$ . As  $t^u(I_k^u) = [0, 1]$ , there is  $y \in I_k^u$  s.t.

$$|t^u(x) - t^u(y)| < \frac{\epsilon}{2}$$

4. (b) Let  $U, \bar{V} \subset \mathbb{R}^n$  open.  
 Show:  $\exists u \in \mathbb{R}^n$  s.t.  $g^u(U) \cap \bar{V} \neq \emptyset$

Set  $\hat{U} = h^{-1}(U)$  and  $\hat{V} = h^{-1}(\bar{V})$

where  $h: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is the homeomorphism that  
 conjugates  $f$  and  $g$ , i.e.  $h \circ f = g \circ h$

$\hat{U}, \hat{V}$  are open as  $h$  is contin.

$f$  is top trans.

i.e.  $\exists x \in \hat{U}$  with  $f(x) \in \hat{V}$

Set  $y = h(x)$ .

$\rightarrow y \in h(\hat{U}) = U$  and

$$g^u(y) = g^u(h(x)) = h(f(x)) \in h(\hat{V}) = \bar{V}$$